

Bachelor Level / second-semester / Science

Computer Science and Information Technology(MTH163)

(Mathematics II)

Candidates are required to give their answers in their own words as far as practicable.

The figures in the margin indicate full marks.

Full marks: 80

Pass marks: 32

Time: 3 hours

Group A (3 x 10 = 30)

Attempt any THREE questions.

1. When a system of linear equation is consistent and inconsistent? Give an example for each. Test the consistency and solve the system of equations: $x - 2y = 5$, $-x + y + 5z = 2$, $y + z = 0$

$$A = \begin{bmatrix} 5 & 1 & 2 \\ 1 & 0 & 3 \\ 4 & -3 & 8 \end{bmatrix}$$

2. What is the condition of a matrix to have an inverse? Find the inverse of the matrix $A = \begin{bmatrix} 5 & 1 & 2 \\ 1 & 0 & 3 \\ 4 & -3 & 8 \end{bmatrix}$ if it exists.

$$A = \begin{bmatrix} 1 & -6 \\ 1 & -2 \\ 1 & 1 \\ 1 & 7 \end{bmatrix} \text{ and } b = \begin{bmatrix} -1 \\ 2 \\ 1 \\ 6 \end{bmatrix}$$

3. Find the least-square solution of $Ax=b$ for

4. Let T is a linear transformation. Find the standard matrix of T such that

(i) $T: \mathbb{R}^2 \rightarrow \mathbb{R}^4$ by $T(e_1) = (3, 1, 3, 1)$ and $T(e_2) = (-5, 2, 0, 0)$ where $e_1 = (1, 0)$ and $e_2 = (0, 1)$;

(ii) $T: \mathbb{R}^2 \rightarrow \mathbb{R}^4$ rotates point as the origin through $\frac{3\pi}{2}$ radians counter clockwise.

(iii) $T: \mathbb{R}^2 \rightarrow \mathbb{R}^4$ is a vertical shear transformation that maps e_1 into $e_1 - 2e_2$ but leaves vector e_2 unchanged.

Group B (10 x 5 = 50)

Attempt any TEN questions.

$$v_1 = \begin{bmatrix} 1 \\ -1 \\ -2 \end{bmatrix}, v_2 = \begin{bmatrix} 5 \\ -4 \\ -7 \end{bmatrix}, v_3 = \begin{bmatrix} -3 \\ 1 \\ 0 \end{bmatrix} \text{ and } y = \begin{bmatrix} -4 \\ 3 \\ h \end{bmatrix}?$$

5. For what value of h will y be in span $\{v_1, v_2, v_3\}$ if

6. Let us define a linear transformation $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ by $T(x) = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} -x_2 \\ x_1 \end{bmatrix}$. Find the image under

$$T \text{ of } u = \begin{bmatrix} 4 \\ 1 \end{bmatrix}, v = \begin{bmatrix} 2 \\ 3 \end{bmatrix}, \text{ and } u + v = \begin{bmatrix} 6 \\ 4 \end{bmatrix}.$$

7. Let $A = \begin{bmatrix} 2 & 5 \\ -3 & 1 \end{bmatrix}$ and $B = \begin{bmatrix} 4 & -5 \\ 3 & k \end{bmatrix}$. Determine the value (s) of k if any will make $AB = BA$.

8. Define determinant. Compute the determinant without expanding $\begin{vmatrix} -2 & 8 & -9 \\ -1 & 7 & 0 \\ 1 & -4 & 2 \end{vmatrix}$.

9. Define null space . Find the basis for the null space of the matrix $A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 3 & 4 \end{bmatrix}$.

10. Let $B = \{b_1, b_2\}$ and $C = \{c_1, c_2\}$ be bases for a vector V , and suppose $b_1 = -c_1 + 4c_2$ and $b_2 = 5c_1 - 3c_2$. Find the change of coordinate matrix for a vector space and find $[x]_C$ for $x = 5b_1 + 3b_2$.

$$\begin{bmatrix} 6 & 5 \\ -8 & -6 \end{bmatrix}.$$

11. Find the eigen values of the matrix

$$\begin{bmatrix} 2 & 1 \\ 3 & -1 \end{bmatrix}.$$

12. Find the QR factorization of the matrix

13. Define binary operation. Determine whether the binary operation $*$ is associative or commutative or both where $*$ is defined on \mathbb{Q}

by letting $x*y = \frac{x+y}{3}$.

14. Show that the ring is an integral domain.

$$[x]_{\beta} = \begin{bmatrix} -4 \\ 6 \\ -7 \end{bmatrix} \text{ where } \beta = \left\{ \begin{bmatrix} -1 \\ 2 \\ 0 \end{bmatrix}, \begin{bmatrix} 3 \\ -5 \\ 2 \end{bmatrix}, \begin{bmatrix} 4 \\ -7 \\ 3 \end{bmatrix} \right\}.$$

15. Find the vector x determined by the coordinate vector